



**SOME RESULTS ON β -KENMOTSU MANIFOLDS WITH A
NON-SYMMETRIC NON-METRIC CONNECTION**

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Dedicated to the memory of the late Professor Krishan Lal Duggal(1929-2022)

ABSTRACT. The object of the present paper is to study some results on a β -Kenmotsu manifold with a non-symmetric non-metric connection. We obtain the condition for the manifold with a non-symmetric non-metric connection to be projectively flat and conformally flat. Also, it has been demonstrated that the manifold satisfying the condition $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$ is an Einstein manifold. Further, by virtue of this result, we found the condition of Ricci soliton in β -Kenmotsu manifold to be expanding.

Keywords: Non-symmetric non-metric connection, β -Kenmotsu manifold, conformal curvature tensor, Ricci soliton, Einstein manifold, Ricci semi-symmetric.

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1. INTRODUCTION

K. Kenmotsu [14] studied a class of almost contact manifolds and identified it as a Kenmotsu manifold. The fundamental properties of local structure of these manifolds were studied by him [14]. Trans-Sasakian manifolds were introduced by J. A. Oubiña [16], which

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generalizes forms of Sasakian, Kenmotsu and cosymplectic manifolds. A trans-Sasakian manifold of type $(0, 0)$, $(\alpha, 0)$ and $(0, \beta)$ are Cosymplectic, α -Sasakian and β -Kenmotsu manifolds respectively, where α, β are smooth functions. In particular, a trans-Sasakian manifold will be Kenmotsu and Sasakian manifold, if $\alpha = 0, \beta = 1$ and $\alpha = 1, \beta = 0$ respectively. β -Kenmotsu manifold provides a large variety of Kenmotsu manifolds. Recently, Kenmotsu manifolds have been studied by several authors (cf. [8, 6, 11, 13, 23, 24]).

On differentiable manifolds, A. Friedmann and J. A. Schouten [12] first proposed a semi-symmetric linear connection. On Riemannian manifolds, semi-symmetric metric connection was first systematically examined by K. Yano [25], which was further studied by authors, including S. Ahmad and S. I. Hussain [21], M. M. Tripathi [22] and others. Semi-symmetric non-metric connection was established in a Riemannian manifold by N. S. Agashe and M. R. Chafle [1]. In line with this, S. K. Chaubey et al. [2] introduced the notion of non-symmetric non-metric connection. It has been further studied in [4, 5, 7, 17, 18, 19].

A torsion tensor of a connection is a mapping $\mathcal{T}' : \chi(\Omega) \times \chi(\Omega) \rightarrow \chi(\Omega)$ defined by

$$\mathcal{T}'(\mathcal{X}_1, \mathcal{X}_2) = \hat{\nabla}_{\mathcal{X}_1} \mathcal{X}_2 - \hat{\nabla}_{\mathcal{X}_2} \mathcal{X}_1 - [\mathcal{X}_1, \mathcal{X}_2]. \tag{1.1}$$

A connection $\hat{\nabla}$ is symmetric if $\mathcal{T}' = 0$ and it is non-symmetric if $\mathcal{T}' \neq 0$. The connection $\check{\nabla}$ is metric if $\check{\nabla}_{\mathcal{X}} \hat{g} = 0$ and it is non-metric if $\check{\nabla}_{\mathcal{X}} \hat{g} \neq 0$. It was further studied by several geometers [10, 9].

In a Riemannian manifold (Ω^{2n+1}, \hat{g}) , \hat{g} is a Ricci soliton if

$$(\mathcal{L}_{\mathcal{V}} \hat{g})(\mathcal{X}_1, \mathcal{X}_2) + 2\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) + 2\Theta \hat{g}(\mathcal{X}_1, \mathcal{X}_2) = 0, \tag{1.2}$$

$\forall \mathcal{X}_1, \mathcal{X}_2$ and \mathcal{V} on Ω^{2n+1} , where $\mathcal{L}_{\mathcal{V}}$ denote the Lie-derivative along the vector field \mathcal{V} , \mathcal{S}^\dagger is Ricci tensor and Θ is a constant. The Ricci soliton is shrinking, steady and expanding if $\Theta < 0$, $\Theta = 0$ and $\Theta > 0$ respectively.

This paper is organized as follows: In Section 2, we present an informative introduction of β -Kenmotsu manifold. In Section 3, we define non-symmetric non-metric connection. In Section 4, we find the curvature tensor with non-symmetric non-metric connection. In Section 5, we investigate projectively and conformally flat β -Kenmotsu manifolds with defined connection. In Section 6, we show that the manifold with the defined connection satisfying the condition $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$ is an Einstein manifold.

2. PRELIMINARIES

A smooth manifold Ω^{2n+1} is almost contact metric [15] if it admits a $(1, 1)$ -tensor field $\hat{\varphi}$, an associated vector field $\hat{\zeta}$, a 1-form $\hat{\eta}$ and the Riemannian metric \hat{g} satisfying

$$\hat{\varphi}^2 \mathcal{X}_1 = -\mathcal{X}_1 + \hat{\eta}(\mathcal{X}_1) \hat{\zeta}, \quad \hat{\eta}(\hat{\zeta}) = 1, \quad \hat{\varphi}\hat{\zeta} = 0, \quad \hat{\eta}(\hat{\varphi}\mathcal{X}_1) = 0, \quad (2.3)$$

$$\hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2) = \hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2), \quad \hat{g}(\mathcal{X}_1, \hat{\zeta}) = \hat{\eta}(\mathcal{X}_1), \quad (2.4)$$

for all $\mathcal{X}_1, \mathcal{X}_2 \in \mathcal{T}'\Omega$.

An almost contact metric manifold Ω^{2n+1} is a β -Kenmotsu manifold [20] if and only if

$$(\hat{\nabla}_{\mathcal{X}_1} \hat{\varphi})\mathcal{X}_2 = \beta[\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta} - \hat{\eta}(\mathcal{X}_2) \hat{\varphi}(\mathcal{X}_1)]. \quad (2.5)$$

From (2.5), we have

$$\hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} = \beta[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \quad (2.6)$$

$$(\hat{\nabla}_{\mathcal{X}_1} \hat{\eta})\mathcal{X}_2 = \beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2) = \beta[\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2)]. \quad (2.7)$$

Further, the curvature tensor \mathcal{R}^\dagger , Ricci tensor \mathcal{S}^\dagger and Ricci operator \mathcal{Q}^\dagger in β -Kenmotsu manifold with the Levi-Civita connection $\hat{\nabla}$ satisfy [20].

$$\begin{aligned} \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta} &= -\beta^2[\hat{\eta}(\mathcal{X}_2) \mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \mathcal{X}_2] + (\mathcal{X}_1\beta)[\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2) \hat{\zeta}] \\ &\quad - (\mathcal{X}_2\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \end{aligned} \quad (2.8)$$

$$\mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1) \mathcal{X}_2 = (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_2) \mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta}], \quad (2.9)$$

$$\mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1) \hat{\zeta} = (\beta^2 + \hat{\zeta}\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \quad (2.10)$$

$$\mathcal{S}^\dagger(\mathcal{X}_1, \hat{\zeta}) = -(2n\beta^2 + \hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_1) - (2n-1)(\mathcal{X}_1\beta), \quad (2.11)$$

$$\mathcal{S}^\dagger(\hat{\zeta}, \hat{\zeta}) = -(2n\beta^2 + \hat{\zeta}\beta), \quad (2.12)$$

$$\mathcal{Q}^\dagger \hat{\zeta} = -(2n\beta^2 + \hat{\zeta}\beta) \hat{\zeta} - (2n-1) \text{grad}\beta. \quad (2.13)$$

Definition 2.1. A β -Kenmotsu manifold Ω^{2n+1} is known as a generalized η -Einstein manifold if its Ricci tensor \mathcal{S}^\dagger of type $(0, 2)$ satisfies

$$\mathcal{S}^\dagger = \lambda_1 \hat{g} + \lambda_2 \hat{\eta} \otimes \hat{\eta} + \lambda_3 [\hat{\eta} \otimes \omega + \omega \otimes \hat{\eta}], \quad (2.14)$$

where, λ_1, λ_2 and λ_3 are smooth functions, ω is a 1-form defined by $\omega(\mathcal{X}_1) = \hat{g}(\mathcal{X}_1, \rho) \forall \mathcal{X}_1$, ρ and $\hat{\zeta}$ are mutually orthogonal to each other.

Definition 2.2. *The projective curvature tensor of a $(2n + 1)$ -dimensional β -Kenmotsu manifold Ω is given by [4]*

$$\mathcal{P}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n}[\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \tag{2.15}$$

Definition 2.3. *The conformal curvature tensor \mathcal{C}^b of a $(2n + 1)$ -dimensional β -Kenmotsu manifold Ω [20] is given by*

$$\begin{aligned} \mathcal{C}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n-1}[\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &\quad + \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{Q}^\dagger\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{Q}^\dagger\mathcal{X}_2] \\ &\quad + \frac{k}{2n(2n-1)}[\hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2] \end{aligned} \tag{2.16}$$

where \mathcal{R}^\dagger , \mathcal{S}^\dagger , \mathcal{Q}^\dagger and k is the curvature tensor, Ricci tensor, Ricci operator and scalar curvature respectively with $\hat{\nabla}$.

3. NON-SYMMETRIC NON-METRIC CONNECTION

The relation between non-symmetric non-metric connection $\check{\nabla}$ and the Levi-Civita connection $\hat{\nabla}$ [2, 3] is given as

$$\check{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 = \hat{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 + \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta}, \tag{3.17}$$

which satisfies

$$\check{\mathcal{T}}'(\mathcal{X}_1, \mathcal{X}_2) = 2\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} \tag{3.18}$$

and

$$(\check{\nabla}_{\mathcal{X}_1}\hat{g})(\mathcal{X}_2, \mathcal{X}_3) = -\hat{\eta}(\mathcal{X}_3)\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_2)\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_3) \tag{3.19}$$

for arbitrary vector fields \mathcal{X}_1 , \mathcal{X}_2 and \mathcal{X}_3 .

Let Ω^{2n+1} be a β -Kenmotsu manifold with a non-symmetric non-metric connection $\check{\nabla}$, then

$$(\check{\nabla}_{\mathcal{X}_1}\hat{\varphi})(\mathcal{X}_2) = (\hat{\nabla}_{\mathcal{X}_1}\hat{\varphi})(\mathcal{X}_2) + \hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2)\hat{\zeta}, \tag{3.20}$$

$$(\check{\nabla}_{\mathcal{X}_1}\hat{\eta})(\mathcal{X}_2) = (\hat{\nabla}_{\mathcal{X}_1}\hat{\eta})(\mathcal{X}_2) - \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2), \tag{3.21}$$

$$\check{\nabla}_{\mathcal{X}_1}\hat{\zeta} = \hat{\nabla}_{\mathcal{X}_1}\hat{\zeta}. \tag{3.22}$$

From (3.22), the following theorem yields:

Theorem 3.1. *The vector field $\hat{\zeta}$ is invariant with respect to the connections $\hat{\nabla}$ and $\check{\nabla}$ [18].*

4. CURVATURE TENSOR ON A β -KENMOTSU MANIFOLD WITH NON-SYMMETRIC
NON-METRIC CONNECTION

If \mathcal{R}^\dagger and $\check{\mathcal{R}}^\dagger$ are the curvature tensors of connections $\hat{\nabla}$ and $\check{\nabla}$ respectively, we have

$$\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \check{\nabla}_{\mathcal{X}_1}\check{\nabla}_{\mathcal{X}_2}\mathcal{X}_3 - \check{\nabla}_{\mathcal{X}_2}\check{\nabla}_{\mathcal{X}_1}\mathcal{X}_3 - \check{\nabla}_{[\mathcal{X}_1, \mathcal{X}_2]}\mathcal{X}_3, \quad (4.23)$$

from (2.5), (2.6) and (3.17), we have

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \beta[2\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\eta}(\mathcal{X}_3)\hat{\zeta} \\ &\quad + \hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \end{aligned} \quad (4.24)$$

Putting $\mathcal{X}_1 = e_i$ in (4.24) and summing over $1 \leq i \leq (2n+1)$, we get

$$\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3) = \mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3) + 2n\beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3), \quad (4.25)$$

$$\check{\mathcal{Q}}^\dagger(\mathcal{X}_2) = \mathcal{Q}^\dagger(\mathcal{X}_2) + 2n\beta(\hat{\varphi}\mathcal{X}_2). \quad (4.26)$$

Thus we state the following theorem:

Theorem 4.1. *In a β -Kenmotsu manifold, Ricci tensor and Ricci operator are defined by the equations (4.25) and (4.26) respectively endowed with $\check{\nabla}$ and $\hat{\nabla}$.*

Contracting (4.25), it follows that

$$\check{k} = k. \quad (4.27)$$

Here $\check{\mathcal{R}}^\dagger$, $\check{\mathcal{S}}^\dagger$, $\check{\mathcal{Q}}^\dagger$ and \check{k} is the curvature tensor, Ricci tensor, Ricci operator and scalar curvature respectively with $\check{\nabla}$.

Thus with the help of (4.27), we have following theorem:

Theorem 4.2. *If a β -Kenmotsu manifold Ω^{2n+1} admits $\check{\nabla}$, then the scalar curvatures corresponding to $\check{\nabla}$ and $\hat{\nabla}$ coincide.*

By replacing $\mathcal{X}_3 = \hat{\zeta}$, in (4.24) and in view of (2.3), (2.4) and (2.8), we get

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} &= \beta^2(\hat{\eta}(\mathcal{X}_1)\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2)\mathcal{X}_1) + 2\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} \\ &\quad + (\mathcal{X}_1\beta)[\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2)\hat{\zeta}] - (\mathcal{X}_2\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}]. \end{aligned} \quad (4.28)$$

From (2.3), (2.9) and (4.24), we get

$$\check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_3 = (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_3)\mathcal{X}_2 - \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\hat{\zeta}] + \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\hat{\zeta}. \quad (4.29)$$

By using (2.3), (2.4), (2.10) and (4.24), we get

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_1)\hat{\zeta} &= \mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1)\hat{\zeta} \\ &= (\beta^2 + \hat{\zeta}\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}]. \end{aligned} \tag{4.30}$$

Putting $\mathcal{X}_3 = \hat{\zeta}$ in (4.25) and using (2.11), we get

$$\begin{aligned} \check{\mathcal{S}}^\dagger(\mathcal{X}_2, \hat{\zeta}) &= \mathcal{S}^\dagger(\mathcal{X}_2, \hat{\zeta}) \\ &= -(2n\beta^2 + \hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_2) - (2n - 1)(\mathcal{X}_2\beta) \end{aligned} \tag{4.31}$$

and

$$\check{\mathcal{Q}}^\dagger(\mathcal{X}_2) = -(2n\beta^2 + \hat{\zeta}\beta)\hat{\zeta} - (2n - 1)grad\beta. \tag{4.32}$$

5. PROJECTIVELY CURVATURE TENSOR ON β -KENMOTSU MANIFOLD WITH NON-SYMMETRIC NON-METRIC CONNECTION

From Definition 2.2, we have

$$\check{\mathcal{P}}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n}[\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \tag{5.33}$$

Using (4.24), (4.25) in (5.33), we acquire

$$\check{\mathcal{P}}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \mathcal{P}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + 2\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\eta}(\mathcal{X}_3)\hat{\zeta}. \tag{5.34}$$

Thus, we have the following results:

Theorem 5.1. *If a β -Kenmotsu manifold Ω^{2n+1} admits $\check{\nabla}$, then the projective curvature tensors corresponding to $\check{\nabla}$ and $\hat{\nabla}$ are related by the equation (5.34).*

If Ω^{2n+1} is $\check{\mathcal{C}}^b$ -flat, then from Definition 2.3 we obtain

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \frac{1}{2n - 1}[\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &\quad + \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\check{\mathcal{Q}}^\dagger\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\check{\mathcal{Q}}^\dagger\mathcal{X}_2] \\ &\quad - \frac{\check{k}}{2n(2n - 1)}[\hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \end{aligned} \tag{5.35}$$

Putting $\mathcal{X}_3 = \hat{\zeta}$ in (5.35) and using (4.25), (4.26), (4.27) and (4.28), we have

$$\begin{aligned} \hat{\eta}(\mathcal{X}_2)\check{\mathcal{Q}}^\dagger\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\check{\mathcal{Q}}^\dagger\mathcal{X}_2 &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})[\hat{\eta}(\mathcal{X}_2)\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\mathcal{X}_2] \\ &\quad - (2n - 1)[(\mathcal{X}_1\beta)\hat{\eta}(\mathcal{X}_2) - (\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_1)]\hat{\zeta} \\ &\quad + 2(2n - 1)\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta}. \end{aligned} \tag{5.36}$$

Again putting $\mathcal{X}_2 = \hat{\zeta}$ in (5.36), we obtain

$$\begin{aligned} \check{Q}^\dagger \mathcal{X}_1 &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})\mathcal{X}_1 - ((2n+1)\beta^2 - (2n-3)\hat{\zeta}\beta + \frac{k}{2n})\hat{\eta}(\mathcal{X}_1)\hat{\zeta} \\ &\quad - (2n-1)((\mathcal{X}_1\beta)\hat{\zeta} + \hat{\eta}(\mathcal{X}_1)\text{grad}\beta). \end{aligned} \quad (5.37)$$

Hence

$$\begin{aligned} \check{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - (2n-1)((\mathcal{X}_1\beta)\hat{\eta}(\mathcal{X}_2) + (\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_1)) \\ &\quad - ((2n+1)\beta^2 - (2n-3)\hat{\zeta}\beta + \frac{k}{2n})\hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2). \end{aligned} \quad (5.38)$$

Let $\omega(\mathcal{X}_1) = \hat{g}(\mathcal{X}_1, \rho) = (\mathcal{X}_1\beta) = \hat{g}(\text{grad}\beta, \mathcal{X}_1) \forall \mathcal{X}_1$. If ρ and $\hat{\zeta}$ are orthogonal then $\hat{\zeta}\beta = 0$ and (5.38) takes the form of (2.14). Therefore, we have the following theorem:

Theorem 5.2. *A conformally flat β -Kenmotsu manifold endowed with $\check{\nabla}$ is a generalised η -Einstein manifold equipped with $\check{\nabla}$.*

6. β -KENMOTSU MANIFOLD SATISFYING $\check{\mathcal{R}}^\dagger \cdot \check{S}^\dagger = 0$

We consider a β -Kenmotsu manifold with $\check{\nabla}$ connection satisfying

$$\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) \cdot \check{S}^\dagger = 0. \quad (6.39)$$

Therefore, we get

$$\check{S}^\dagger(\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3, \mathcal{X}_4) + \check{S}^\dagger(\mathcal{X}_3, \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_4) = 0. \quad (6.40)$$

Replacing \mathcal{X}_1 by $\hat{\zeta}$ in (6.40), it follows that

$$\check{S}^\dagger(\check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_3, \mathcal{X}_4) + \check{S}^\dagger(\mathcal{X}_3, \check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_4) = 0. \quad (6.41)$$

In view of (4.29), we have

$$\begin{aligned} &(\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_3)\check{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) - \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\check{S}^\dagger(\hat{\zeta}, \mathcal{X}_4)] \\ &+ \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\check{S}^\dagger(\hat{\zeta}, \mathcal{X}_4) + (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \mathcal{X}_2) \\ &- \hat{g}(\mathcal{X}_2, \mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \hat{\zeta})] + \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \hat{\zeta}) = 0. \end{aligned} \quad (6.42)$$

Again replacing \mathcal{X}_3 by $\hat{\zeta}$ and using (2.3) and (4.31), we have

$$\begin{aligned} \check{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) &= - (2n\beta^2 + \hat{\zeta}\beta)\hat{g}(\mathcal{X}_2, \mathcal{X}_4) + (2n-1)((\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_4) \\ &\quad - (\mathcal{X}_4\beta)\hat{\eta}(\mathcal{X}_2)) + 2n\beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_4). \end{aligned} \quad (6.43)$$

Using (4.25), we have

$$\begin{aligned} \mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) &= -(2n\beta^2 + \hat{\zeta}\beta)\hat{g}(\mathcal{X}_2, \mathcal{X}_4) + (2n - 1)(\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_4) \\ &\quad - (2n - 1)(\mathcal{X}_4\beta)\hat{\eta}(\mathcal{X}_2). \end{aligned} \tag{6.44}$$

Taking $\mathcal{X}_4 = \hat{\zeta}$ in (6.44), we get

$$2(\mathcal{X}_2\beta) = (\hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_2). \tag{6.45}$$

Again we take $\mathcal{X}_2 = \hat{\zeta}$ in (6.45), we get

$$\hat{\zeta}\beta = 0. \tag{6.46}$$

Using (6.45) and (6.46) in (6.44), we have

$$\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) = -2n\beta^2\hat{g}(\mathcal{X}_2, \mathcal{X}_4). \tag{6.47}$$

Thus we leads to the theorem:

Theorem 6.1. *A β -Kenmotsu manifold satisfying the condition $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$ with $\check{\nabla}$ is an Einstien manifold with $\hat{\nabla}$.*

A Ricci soliton in β -Kenmotsu manifold is defined by equation (1.2). Naturally, two cases appear corresponding to the vector field $\mathcal{V} : \mathcal{V} \in Span\hat{\zeta}$ and $\mathcal{V} \perp \hat{\zeta}$. We consider only the case $\mathcal{V} = \hat{\zeta}$. The Ricci soliton $(\hat{g}, \hat{\zeta}, \Theta)$ on a β -Kenmotsu manifold endowed with $\check{\nabla}$ is defined as

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) + 2\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) + 2\Theta\hat{g}(\mathcal{X}_1, \mathcal{X}_2) = 0. \tag{6.48}$$

Here

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) = (\check{\nabla}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) + \hat{g}(\check{\nabla}_{\mathcal{X}_1}\hat{\zeta}, \mathcal{X}_2) + \hat{g}(\mathcal{X}_1, \check{\nabla}_{\mathcal{X}_2}\hat{\zeta}). \tag{6.49}$$

Now using (2.6) and (3.22) in (6.49), we have

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) = 2\beta[\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2)]. \tag{6.50}$$

Now, from (6.48) and (6.50), we obtain

$$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = -(\beta + \Theta)\hat{g}(\mathcal{X}_1, \mathcal{X}_2) + \beta\hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2). \tag{6.51}$$

Replacing $\mathcal{X}_1, \mathcal{X}_2$ by $\hat{\zeta}$ and using (6.43), we get

$$\Theta = 2n(\beta^2 + \hat{\zeta}\beta).$$

Since β is some non-zero function, we have $\Theta \neq 0$, so we state the following theorem:

Theorem 6.2. *A Ricci soliton $(\hat{g}, \hat{\zeta}, \Theta)$ in β -Kenmotsu manifold Ω^{2n+1} with $\hat{\nabla}$ can not be steady but is expanding if $\beta^2 + \hat{\zeta}\beta > 0$ and shrinking if $\beta^2 + \hat{\zeta}\beta < 0$.*

7. EXAMPLE OF β -KENMOTSU MANIFOLD WITH NON-SYMMETRIC NON-METRIC CONNECTION

Example 7.1. *Let us consider the 3-dimensional manifold $\Omega^{2n+1} = [(x; y; z) \in \mathcal{R}^3 | z \neq 0]$; where $(x; y; z)$ are the standard coordinates in \mathcal{R}^3 . Consider the vector fields*

$$\varrho_1 = z^2 \frac{\partial}{\partial x}, \quad \varrho_2 = z^2 \frac{\partial}{\partial y}, \quad \varrho_3 = \frac{\partial}{\partial z} = \hat{\zeta}.$$

At each point of Ω^{2n+1} , ϱ_1, ϱ_2 and ϱ_3 are linearly independent. Suppose the Riemannian metric \hat{g} is defined as

$$\begin{aligned} \hat{g}(\varrho_1, \varrho_2) &= \hat{g}(\varrho_2, \varrho_3) = \hat{g}(\varrho_3, \varrho_1) = 0, \\ \hat{g}(\varrho_1, \varrho_1) &= \hat{g}(\varrho_2, \varrho_2) = \hat{g}(\varrho_3, \varrho_3) = 1, \end{aligned} \tag{7.52}$$

and $\hat{\varphi}$ is defined by

$$\hat{\varphi}(\varrho_1) = -\varrho_2, \quad \hat{\varphi}(\varrho_2) = \varrho_1, \quad \hat{\varphi}(\varrho_3) = 0. \tag{7.53}$$

According to the Lie bracket definition, we get

$$[\varrho_1, \varrho_2] = 0, \quad [\varrho_1, \varrho_3] = -\frac{2}{z}\varrho_1, \quad [\varrho_2, \varrho_3] = -\frac{2}{z}\varrho_2. \tag{7.54}$$

Also

$$\begin{aligned} 2\hat{g}(\hat{\nabla}_{\mathcal{X}_1}\mathcal{X}_2, \mathcal{X}_3) &= \mathcal{X}_1\hat{g}(\mathcal{X}_2, \mathcal{X}_3) + \mathcal{X}_2\hat{g}(\mathcal{X}_3, \mathcal{X}_1) - \mathcal{X}_3\hat{g}(\mathcal{X}_1, \mathcal{X}_2) \\ &+ \hat{g}([\mathcal{X}_1, \mathcal{X}_2], \mathcal{X}_3) - \hat{g}([\mathcal{X}_2, \mathcal{X}_3], \mathcal{X}_1) + \hat{g}([\mathcal{X}_3, \mathcal{X}_1], \mathcal{X}_2). \end{aligned} \tag{7.55}$$

Using Koszul's formula, we get

$$\begin{aligned} \hat{\nabla}_{\varrho_1}\varrho_1 &= \frac{2}{z}\varrho_3, \quad \hat{\nabla}_{\varrho_1}\varrho_2 = 0, \quad \hat{\nabla}_{\varrho_1}\varrho_3 = -\frac{2}{z}\varrho_1, \\ \hat{\nabla}_{\varrho_2}\varrho_1 &= 0, \quad \hat{\nabla}_{\varrho_2}\varrho_2 = \frac{2}{z}\varrho_3, \quad \hat{\nabla}_{\varrho_2}\varrho_3 = -\frac{2}{z}\varrho_2, \\ \hat{\nabla}_{\varrho_3}\varrho_1 &= 0, \quad \hat{\nabla}_{\varrho_3}\varrho_2 = 0, \quad \hat{\nabla}_{\varrho_3}\varrho_3 = 0. \end{aligned} \tag{7.56}$$

Also $\mathcal{X}_1 = \mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3$ and $\hat{\zeta} = \varrho_3$, then we have

$$\begin{aligned} \hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \hat{\nabla}_{\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3} \varrho_3 \\ &= \mathcal{X}^1 \hat{\nabla}_{\varrho_1} \varrho_3 + \mathcal{X}^2 \hat{\nabla}_{\varrho_2} \varrho_3 + \mathcal{X}^3 \hat{\nabla}_{\varrho_3} \varrho_3 \\ &= -\frac{2}{z} (\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2) \end{aligned} \tag{7.57}$$

and

$$\begin{aligned} \hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \beta[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}] \\ &= \beta[(\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3) - \hat{g}(\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3, \varrho_3) \varrho_3] \\ &= -\frac{2}{z} [\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3 - \mathcal{X}^3 \varrho_3] \\ &= -\frac{2}{z} [\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2]. \end{aligned} \tag{7.58}$$

From (7.57) and (7.58), the structure $(\hat{\varphi}, \hat{\zeta}, \hat{\eta}, \hat{g})$ is a β -Kenmotsu manifold structure. Therefore $\Omega^3(\hat{\varphi}, \hat{\zeta}, \hat{\eta}, \hat{g})$ is a β -Kenmotsu manifold. From (2.3), (2.5), (3.17) and (7.56), we have

$$\begin{aligned} \check{\nabla}_{\varrho_1} \varrho_1 &= \frac{2}{z} \varrho_3, & \check{\nabla}_{\varrho_1} \varrho_2 &= -\varrho_3, & \check{\nabla}_{\varrho_1} \varrho_3 &= -\frac{2}{z} \varrho_1, \\ \check{\nabla}_{\varrho_2} \varrho_1 &= \varrho_3, & \check{\nabla}_{\varrho_2} \varrho_2 &= \frac{2}{z} \varrho_3, & \check{\nabla}_{\varrho_2} \varrho_3 &= -\frac{2}{z} \varrho_2, \\ \check{\nabla}_{\varrho_3} \varrho_1 &= 0, & \check{\nabla}_{\varrho_3} \varrho_2 &= 0, & \check{\nabla}_{\varrho_3} \varrho_3 &= 0. \end{aligned} \tag{7.59}$$

From equations (3.18) and (3.19), we have

$$\check{\mathcal{T}}'(\varrho_1, \varrho_2) = 2\hat{g}(\hat{\varphi}\varrho_1, \varrho_2) = -2\varrho_3 \neq 0$$

and

$$\begin{aligned} (\check{\nabla}_{\varrho_1} \hat{g})(\varrho_2, \varrho_3) &= -\hat{\eta}(\varrho_3)\hat{g}(\hat{\varphi}\varrho_1, \varrho_2) - \hat{\eta}(\varrho_2)\hat{g}(\hat{\varphi}\varrho_1, \varrho_3) \\ &= 1 \neq 0. \end{aligned}$$

Consequently, a non-symmetric non-metric connection $\check{\nabla}$ is defined in (3.17). Also,

$$\begin{aligned} \check{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \check{\nabla}_{\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3} \varrho_3 \\ &= \mathcal{X}^1 \check{\nabla}_{\varrho_1} \varrho_3 + \mathcal{X}^2 \check{\nabla}_{\varrho_2} \varrho_3 + \mathcal{X}^3 \check{\nabla}_{\varrho_3} \varrho_3 \\ &= -\frac{2}{z} \mathcal{X}^1 \varrho_1 - \frac{2}{z} \mathcal{X}^2 \varrho_2, \end{aligned} \tag{7.60}$$

The equation (3.22) can be verified using equations (7.57) and (7.60).

The components of \mathcal{R}^\dagger of $\hat{\nabla}$ are defined as

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_1 = \frac{4}{z^2}\varrho_2, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_1 = \frac{4}{z^2}\varrho_3, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_1 = 0,$$

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_2 = -\frac{4}{z^2}\varrho_1, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_2 = 0, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_2 = \frac{4}{z^2}\varrho_3, \quad (7.61)$$

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_3 = 0, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_1, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_2,$$

hence we can verify the equations (2.8), (2.9), (2.10) and (2.12).

Similarly, the components of curvature tensor $\check{\mathcal{R}}^\dagger$ of connection $\check{\nabla}$ are as under:

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_1 = \frac{4}{z^2}\varrho_2 - \frac{2}{z}\varrho_1, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_1 = \frac{4}{z^2}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_1 = \frac{2}{z}\varrho_3,$$

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_2 = -\frac{4}{z^2}\varrho_1 - \frac{2}{z}\varrho_2, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_2 = -\frac{2}{z}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_2 = \frac{4}{z^2}\varrho_3, \quad (7.62)$$

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_3 = \frac{4}{z}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_1, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_2.$$

Thus, we can verify (4.24), (4.28), (4.29) and (4.30).

$\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2)$ of connection $\hat{\nabla}$ can be derived by using (7.61) in

$\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = \sum_{i=1}^3 \hat{g}(\mathcal{R}^\dagger(\varrho_i, \mathcal{X}_1)\mathcal{X}_2, \varrho_i)$. It is as under:

$$\mathcal{S}^\dagger(\varrho_1, \varrho_1) = \mathcal{S}^\dagger(\varrho_2, \varrho_2) = \mathcal{S}^\dagger(\varrho_3, \varrho_3) = -\frac{8}{z^2}. \quad (7.63)$$

$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_1)$ of connection $\check{\nabla}$ can be derived by using equation (7.62) in

$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = \sum_{i=1}^3 \check{g}(\check{\mathcal{R}}^\dagger(\varrho_i, \mathcal{X}_1)\mathcal{X}_2, \varrho_i)$. It is as follows:

$$\check{\mathcal{S}}^\dagger(\varrho_1, \varrho_1) = \check{\mathcal{S}}^\dagger(\varrho_2, \varrho_2) = \check{\mathcal{S}}^\dagger(\varrho_3, \varrho_3) = -\frac{8}{z^2}. \quad (7.64)$$

In view of (7.63) and (7.64), the scalar curvature can be calculated as under:

$$k = \sum_{i=1}^3 \mathcal{S}^\dagger(\varrho_i, \varrho_i) = \mathcal{S}^\dagger(\varrho_1, \varrho_1) + \mathcal{S}^\dagger(\varrho_2, \varrho_2) + \mathcal{S}^\dagger(\varrho_3, \varrho_3) = -\frac{24}{z^2},$$

$$\check{k} = \sum_{i=1}^3 \check{\mathcal{S}}^\dagger(\varrho_i, \varrho_i) = \check{\mathcal{S}}^\dagger(\varrho_1, \varrho_1) + \check{\mathcal{S}}^\dagger(\varrho_2, \varrho_2) + \check{\mathcal{S}}^\dagger(\varrho_3, \varrho_3) = -\frac{24}{z^2}.$$

Thus we see that the example also verify Theorem 4.2.

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